

MFES - Métodos Formais em Engenharia de Software

Alloy

Ana Paiva

apaiva@fe.up.pt www.fe.up.pt/~apaiva

Modeling with Alloy

- **Statics:** Exploring states
 - Signatures
 - Facts
- **Dynamics:** Adding operations
 - Operations
 - Functions

Alloy

- A model in Alloy is an object model: a set of atoms (objects) connected through relations.
- Running a predicate:
 - Checks satisfiability: tries to find a model that satisfies the predicate
 - If no model is found, the specification may be inconsistent.
 - Interactively returns all models that satisfy the predicate (if any) within a limited scope.
- Checking an assertion:
 - Checks validity: tries to find a counter-example that violates the assertion
 - If no counter-example is found, the specification may be valid.

Checking satisfiability

```
pred Name {  
    <formulas>  
}
```

```
run Name for <scope>
```

Checking validity

```
assert Name {
  <formulas>
}
```

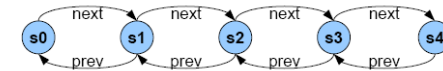
check Name for <scope>

Ordering module

Establishes linear ordering over atoms of signature S

```
open util/ordering[S]
```

$$S = s0 + s1 + s2 + s3 + s4$$



```
first() = s0
last() = s4
next(s2) = s3
prev(s2) = s1
nexts(s2) = s3 + s4
prevs(s2) = s0 + s1
```

```
lt(s1, s2) = true
lt(s1, s1) = false
gt(s1, s2) = false
lte(s0, s3) = true
lte(s0, s0) = true
gte(s2, s4) = false
```

Modeling dynamics

- Representing state with signatures:
sig State { ... }
- Representing initial conditions as predicates:
pred init[s : State] { ... }
- Representing operations as predicates:
pred op_1[s, s': State, a: Data_1, ...] { ... }
pred op_2[s, s': State, a: Data_2, ...] { ... }
...
pred op_n[s, s': State, a: Data_n, ...] { ... }

Modeling dynamics

- Pre- and post-conditions:
pred op_1[s, s': State, ...] {
 precondition[s]
 postcondition[s,s']
}
- Generating traces (imposing an ordering on states)
open util/ordering[State]
...
fact traces {
 init[first]
 all s : State - last |
 let s' = s.next | op_1[s,s',...] or op_2[s,s',...] or ... or op_n[s,s',...]
}

Modeling dynamics

- Representing invariants as predicates or facts:
fact invariant1 { ... }
pred invariant2[s : State,...] { ... }
- Checking whether an invariant is preserved by an operation:
assert Op1PreservesInvariant2 {
 all s, s': State, a: Data_1 |
 invariant2[s] and op_1[s,s',a] implies invariant2[s']
}
- Checking that the invariant is established by an initial state
assert initEstablishesInvariant {
 all s: State | init[s] implies invariant2[s]
}

Some examples

The shepherd, the wolf, the sheep and cabbage

- A shepherd, accompanied by a sheep, a wolf and a huge cabbage, close to the edge of a river he must cross. Faced him a boat so small that ...
- ...at a time he can only bring himself and one of his companions. But if you let the sheep and cabbage alone in a room, the cabbage will be devoured by the sheep...
- How will you organize the trips of the shepherd in order to be on the other side with his three companions?

The shepherd, the wolf, the sheep and cabbage (statics)

```
// the solution for this problem is a sequence of states
open util/ordering[State]

// There are some things that eat other things
abstract sig Thing{
  eat : set Thing
}

// The things that are important in this example are wolf, sheep
// and cabbage
one sig Wolf, Sheep, Cabbage extends Thing {}
```

The shepherd, the wolf, the sheep and cabbage (statics)

```
// fact: The wolf eat sheeps and the sheeps eat cabbages
fact { eat = (Wolf -> Sheep) + (Sheep -> Cabbage) }

// the river has two edges: right and left
abstract sig Edge{}
one sig Right, Left extends Edge {}

// the state of the system keeps the edge where the shepherd is
// and the edge where the other things are
sig State {
  shepherd: Edge,
  local : Thing -> one Edge
}
```

The shepherd, the wolf, the sheep and cabbage (statics)

```
// the edge where the shepherd is not, cannot have things that
// eat each other
fact {
  all s : State, x,y : (s.local).(Edge - s.shepherd) | x not in y.eat
}

// Satisfiability ?
run {} for 3 but 5 State
```

The shepherd, the wolf, the sheep and cabbage (dynamics)

```
// The shepherd changes edge alone
pred alone[s, s' : State] {
  s'.local = s.local
  s'.shepherd != s.shepherd
}
run alone for 3

// o barqueiro muda de margem acompanhado
pred withcompany[s, s' : State] {
  one x : Thing { s.shepherd = s.local[x]
    s'.shepherd != s.shepherd
    s'.local[x] = s'.shepherd
    all y : Thing - x | s'.local[y] = s.local[y] }
}
run withcompany for 3 but 2 State
```

The shepherd, the wolf, the sheep and cabbage (dynamics)

```
// In the beginning the things are in the same edge
// the system changes states either when the shepherd changes edge (alone or
// with company)
fact { //this fact could/"should" be expressed as a predicate
  lone Thing.(first.local)
  all s : State, s' : s.next | alone[s,s'] or withcompany[s,s']
}

//How to obtain the solution (sequence of steps performed to change the edge
//of all things)?
// There is no state where the edge is different from the edge in the beginning
// so it is impossible to change edge
assert ThereIsNoSolution {
  no s : State | Thing.(s.local) = Edge - Thing.(first.local)
}

check ThereIsNoSolution for 3 but 8 State
```

The shepherd, the wolf, the sheep and cabbage

