



Ant Colony Optimization

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Outline

- Swarm Intelligence
- Introduction to Ant Colony Optimization (ACO)
- Ant Behaviour
- Stigmergy
- Pheromones
- Basic Algorithm
- Example
- Advantages and Disadvantages
- References

Swarm Intelligence

- Artificial intelligence technique based on the study of collective behavior in decentralized, self-organized systems
- Introduced by Beni & Wang in 1989
- **Collective system** capable of performing complex tasks in a dynamic environment
- Model suited to **distributed problem solving**
- Works without:
 - External guidance
 - Central coordination
- Typically made up of a population of **simple** agents

Swarm Intelligence



Ant Colony Optimization

- Proposed by **Marco Dorigo** in 1991
- Inspired in the behavior of real ants
- **Multi-agent approach** for solving complex combinatorial optimization problems
- Applications:
 - Traveling Salesman Problem
 - Scheduling
 - Network Model Problem
 - Vehicle routing

Ant Behavior

Nest



Obstacle



Food

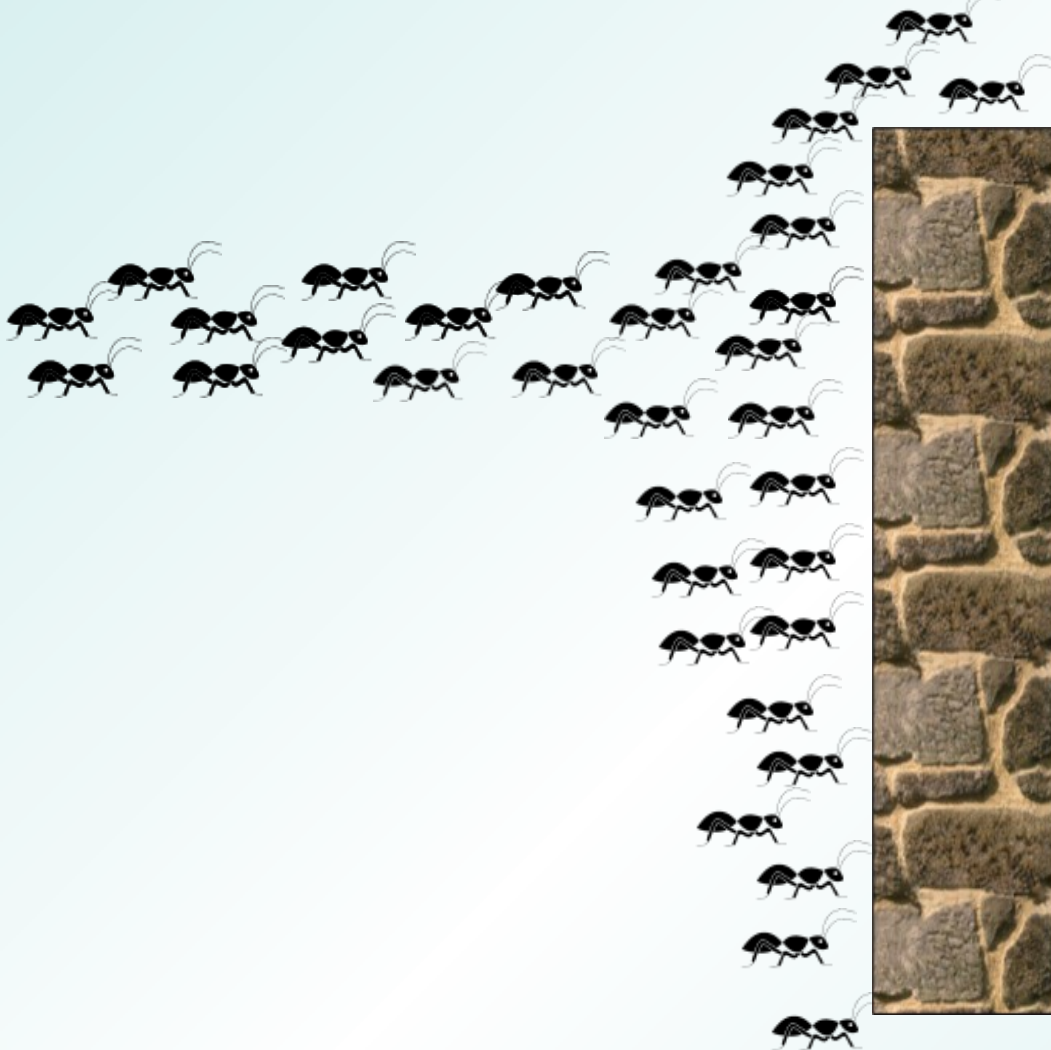


Ant Behavior

Nest

Obstacle

Food



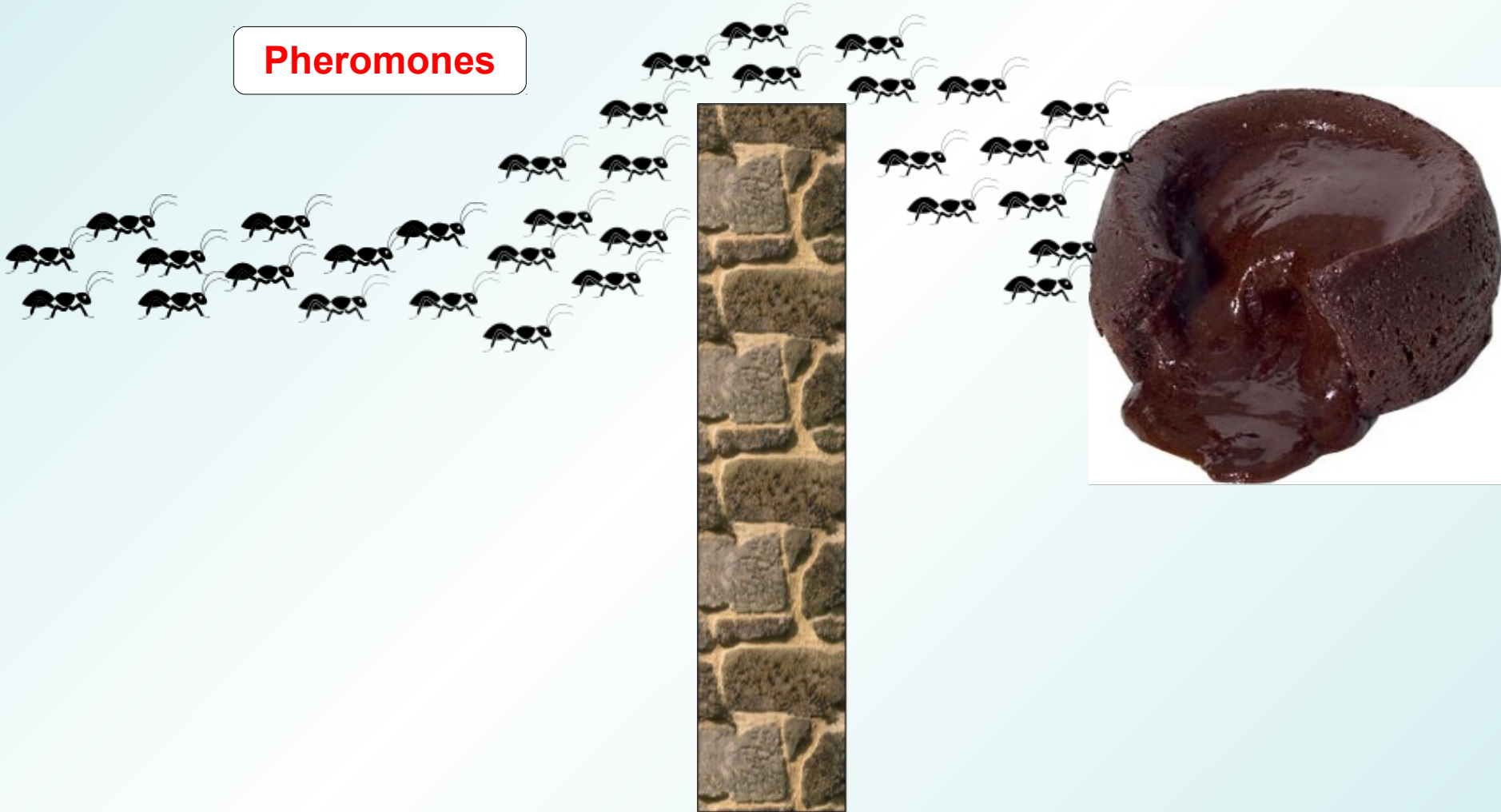
Ant Behavior

Nest

Pheromones

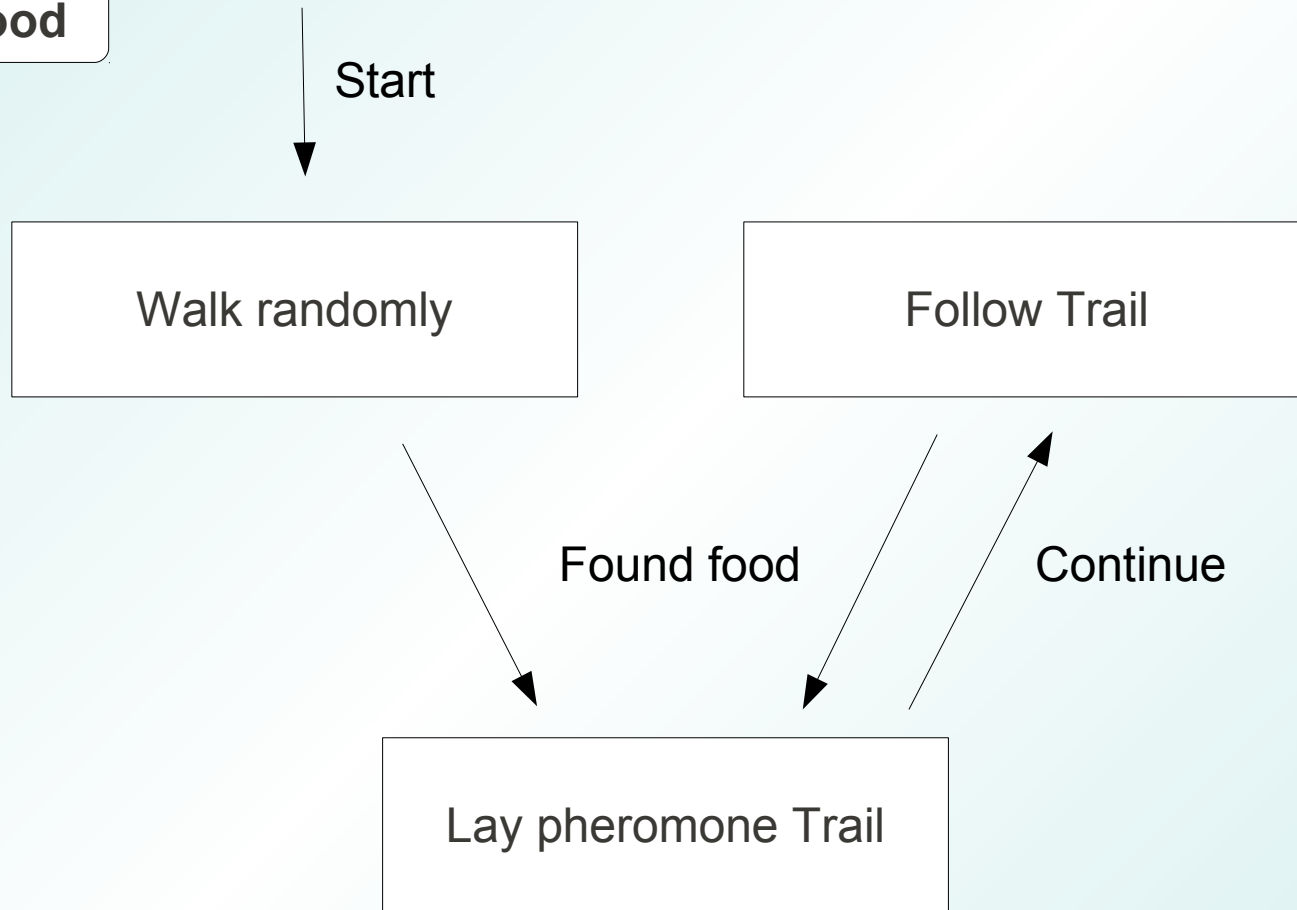
Obstacle

Food



Ant Behavior

Quest for food



Ant Behavior

- Ant behavior is **stochastic**
- The behavior is induced by **indirect communication** (pheromone paths) - **Stigmergy**
- Ants explore the search space
- Limited ability to sense local environment
- Act **concurrently** and **independently**
- High quality solutions emerge via **global cooperation**

Stigmergy

- Term coined by French biologist Pierre-Paul Grasse, means interaction through the environment
- Indirect communication via **interaction with environment**
- Agents **respond to changes** in the environment
- Allows simpler agents
- Decreases direct communication

Pheromones

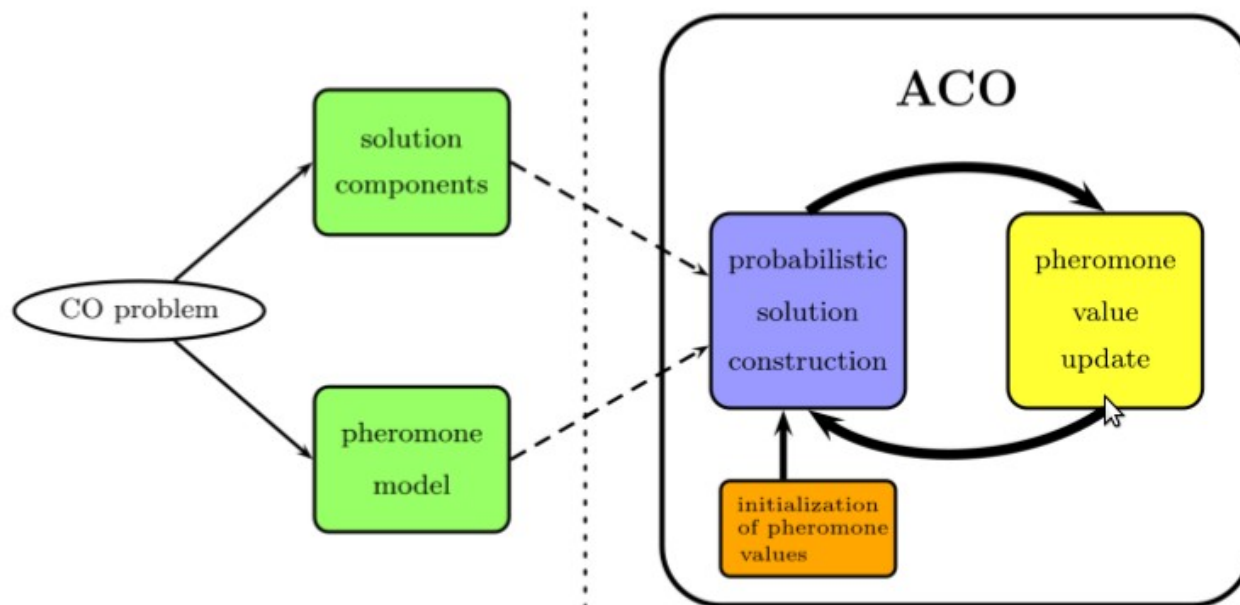
- Ants lay pheromone trails while traveling
- Pheromones **accumulate** with multiple ants using a path
- This behavior leads to the appearance of **shortest paths**

Pheromones = **long-term memory** of an ant colony

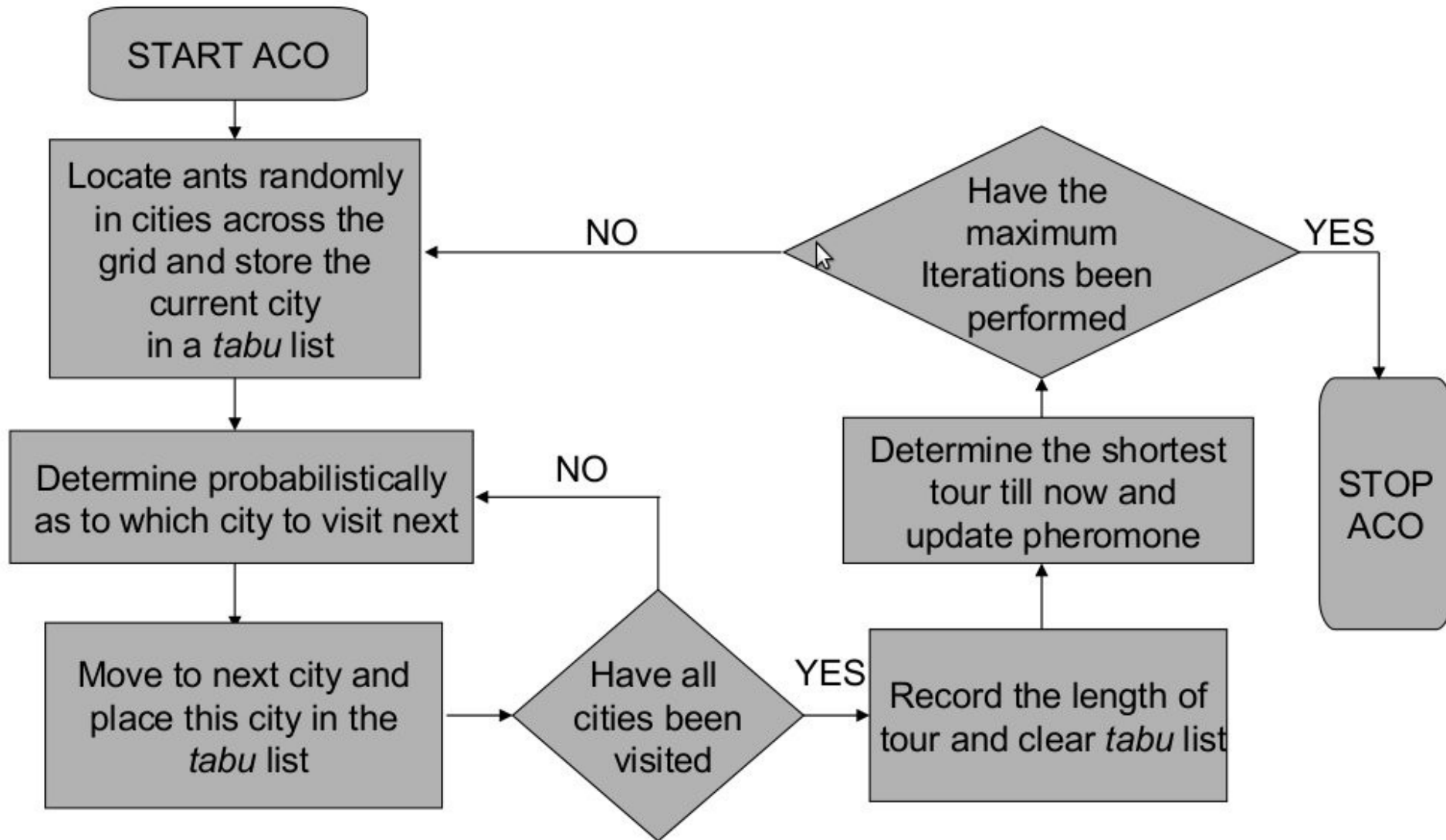
- Pheromones **evaporate**
 - **Avoids being trapped** in local optima
 - ρ small \Rightarrow low evaporation \Rightarrow **slow adaptation**
 - ρ large \Rightarrow high evaporation \Rightarrow **fast adaptation**

ACO Algorithm

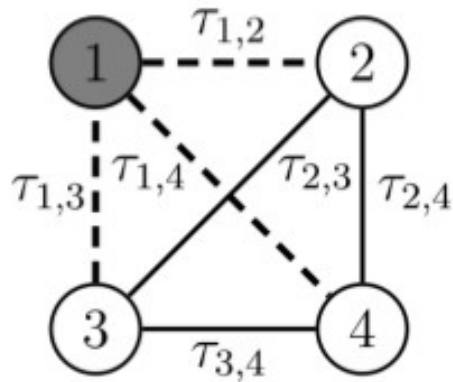
- **Construct solutions**
 - Explore the search space
 - Choose next step **probabilistically** according to the **pheromone model**
- Apply local search to constructed solutions (Optional)
- **Update pheromones** (add new + evaporate)



Example: TSP

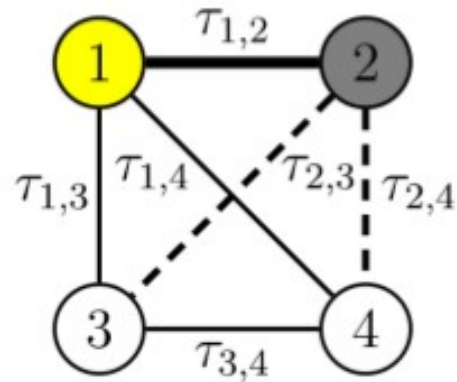


Example: TSP



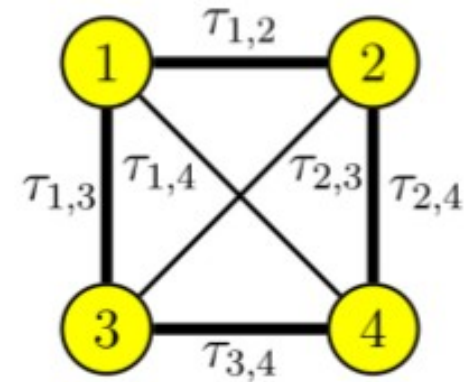
$$\mathbf{p}(e_{1,j}) = \frac{\tau_{1,j}}{\tau_{1,2} + \tau_{1,3} + \tau_{1,4}}$$

(a) First step of the solution construction.



$$\mathbf{p}(e_{2,j}) = \frac{\tau_{2,j}}{\tau_{2,3} + \tau_{2,4}}$$

(b) Second step of the solution construction.



(c) The complete solution after the final construction step.

Advantages and Disadvantages

- Advantages

- Can be used in **dynamic** applications
- **Positive Feedback** leads to rapid discovery of good solutions
- **Distributed computation** avoids premature convergence

- Disadvantages

- Convergence is **guaranteed**, but **time** to convergence **uncertain**
- Coding is not straightforward

References

- Dorigo M., Blum C., *Ant colony optimization theory: A survey*, Theoretical Computer Science, Volume 344, Issues 2-3, November 2005
- Blum C., *Ant colony optimization: Introduction and recent trends*, Physics of Life Reviews, Volume 2, Issue 4, December 2005
- Dorigo M., Stutzle T., *Ant Colony Optimization*, Ant Colony Optimization, MIT Press 2004



AntPacking – An Ant Colony Optimization Approach for the One-Dimensional Bin Packing Problem

by B. Brugger, K. Doerner , R. Hartl and M. Reimann

Introduction

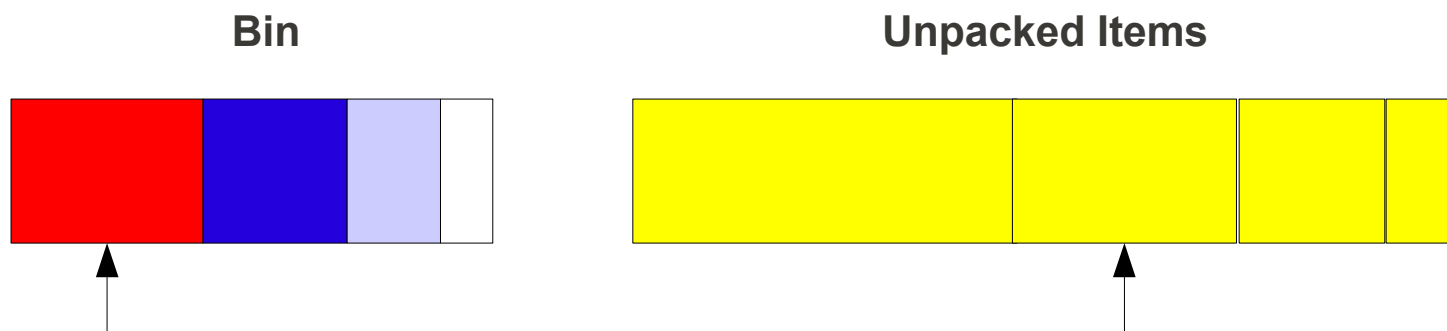
- Deals with the **one-dimensional** BPP
- Meta-heuristic solution approach based on Ant Colony Optimization
- A set of ants repeatedly build and improve solutions
- Ants update joint memory, **guiding** future searches
- Memory update is based on **solution quality**

Pheromone Decoding

- Items are grouped according to their **size**
- Relates the size of an item to be packed to the **filling degree** of the current bin
- They only consider how much **space is left** in the bin
- The importance of filling a bin is emphasized

Solution Construction and Local Search

- A ant fills bins until all items are packed
- The decision about which item to add is based on:
 - **FFD** rule
 - **Pheromone** information
- **Local search** is performed when a ant finishes filling a bin
 - Tries to replace **one bin item** with an **unpacked item** if this leads to **less free space**
 - Stops when the bin is full or no improving moves are available



Fitness Function and Pheromone Update

- The fitness function **guides** the search
- Fitness is calculated for each bin
- Only **full bins** receive pheromone
- **Each ant** is allowed to modify the memory (**pheromone update**)
- All the solution elements are subject to **evaporation**

Dataset and Preprocessing

- Benchmark instances properties:
 - bin capacity $C = 150$
 - item sizes bounded by $[20, 100]$
- Procedure was applied to **reduce the ants search effort**
- Eliminates mainly **large items**
- Problem size is **reduced** and consequently **easier to solve**

Computational Analysis

- Algorithm coded in **C** and executed on a Pentium 3, 750 MHz
- Number of ants fixed to **10**
- Time limit for termination of the algorithm set to **60 seconds**
- Computational test:
 - Benchmark comparison with **Hybrid Grouping Genetic Algorithm** (HGGA) and the **Hybrid ACO** (HACO)

Algorithm Comparison

Problem class	HACO		HGGA		AntPacking	
	# of optima	seconds	# of optima	seconds	# of optima	seconds
u120	20	1	20	0.31	20	0.04
u250	18	52	20	0.75	20	0.58
u500	20	50	20	1.5	20	1.11
u1000	20	147	20	3.78	20	3.88

Conclusion

- New pheromone decoding scheme and update strategy
- Results show **excellent performance**
- AntPacking approach performs **at least as good** as the HGGA which is considered to be the best algorithm for BPPs